Amendments to the Claims:

This listing of claims will replace all prior versions, and listings of claims in the application:

Listing of Claims:

Please amend the claims as shown.

1. (Currently Amended) An integrated view system comprising:

at least one stereo-camera installed in a vehicle for taking images of predetermined outside area;

a stereo-image recognizer for processing a pair of images taken by the stereo-camera to recognize objects that are obstacles to the front, thus generating obstacle data;

an integrated view data generator for generating integrated view data including three-dimensional view data based on the pair of images taken by the stereo-camera and the obstacle data from the stereo-image recognizer; and

an integrated image display for displaying the integrated view data as visible images to crew in the vehicle,

wherein the integrated view data generator is capable of removing the three-dimensional ~~vision~~ view data from the integrated view data by turning off the stereo-camera while retaining the obstacle data.

2. (Previously Presented) The integrated view system according to claim 1, wherein the integrated view data generator adds peripheral wide-area view data to the three-dimensional view data.

3. (Previously Presented) The integrated view system according to claim 1, wherein the integrated view data generator includes a head mount display for overlapping the visible images of the integrated view data and actual view.

4. (Cancelled)

5. (Previously Presented) The integrated view system according to claim 1, wherein the stereo-camera includes two infrared cameras arranged as separated from each other by a distance corresponding to a specific base line.

6. (Previously Presented) The integrated view system according to claim 1 further comprising at least a first stereo-camera and a second stereo-camera, the first stereo camera being an infrared camera and the second stereo camera being an intensifier, the first and the second stereo-cameras being selectively used in accordance with actual views.

7. (Currently Amended) An integrated vision system comprising:

at least one stereo-camera installed in a vehicle for taking images of a predetermined outside area;

a stereo-image recognizer for processing a pair of images taken by the stereo-camera to recognize objects that are obstacles to the front of the vehicle, thus generating obstacle data;

an integrated view data generator for generating integrated view data including three-dimensional view data based on the pair of images taken by the stereo-camera and the obstacle data including at least one symbolized obstacle or one emphasized obstacle from the stereo-image recognizer; and

an integrated image display for displaying the integrated view data as visible images to crew in the vehicle, wherein the integrated view data generator is capable of removing the three-

dimensional ~~vision~~ view data from the integrated view data by turning off the stereo-camera while retaining the obstacle data .

8. (Cancelled)

9. (Previously Presented) An integrated view system comprising:

at least one stereo-camera installed in a vehicle for taking images of predetermined outside area;

a stereo-image recognizer for processing a pair of images taken by the stereo-camera to recognize objects that are obstacles to the front, thus generating obstacle data;

a geographical image generator for generating a geographical image viewed from viewing points of a pilot or crew;

an integrated view data generator for generating integrated view data including three-dimensional view data based on the pair of images taken by the stereo-camera, the obstacle data including at least one symbolized obstacle or one emphasized obstacle from the stereo-image recognizer; and the geographical image from the geographical image generator; and

an integrated image display for displaying the integrated view data as visible images by overlapping with an actual view from a cockpit.